NUMERICAL STUDY OF A STEEL SUB-FRAME IN FIRE

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Abstract. *Steel framed buildings are generally designed with "simple" shear-resisting connections, and lateral forces are resisted by vertical bracing and shear walls. When a beam is considered then the effects of the longitudinal restraints by the adjacent structure and the rotational restraint by the connections has to be taken into account. Because of structural interaction, the beam behaviour at elevated temperature is rather complex.*

This paper presents a numerical parametric study of a structural system consisting of an exposed steel beam restrained between a pair of fire protected steel columns. The structural sub-frame is modelled using 3D shell elements, thereby taking into account the effect of the local failure modes, and the realistic behaviour of the sub-frame exposed to natural fire. The numerical model accounts for the initial geometrical imperfections, non-linear temperature

gradient over the cross-section, geometrical and material nonlinearity and temperature dependent material properties.

Results obtained using a general Finite Element software - LUSAS and a fire dedicated software – SAFIR, are compared. The influence of following variables: beam span/depth ratio, lateral restraint, gradient temperature within the cross-section and mechanical load level is presented in the paper. The failure modes, the development of the internal forces and displacements throughout the analysis are considered to exemplify the effects of the variables considered.

1   INTRODUCTION

The behaviour of steel members during fire is complex and very much dependent on the restraint at the member ends. In order to capture the beam behaviour during a fire it is therefore required to take a global view and to examine the behaviour of a representative sub-structure [1] that can reproduce the redistribution of forces that takes place as the temperature varies with time. In steel structures, the restraint at member ends depends on the following two aspects: (i) the behaviour of the joints connecting, a beam to a column that is usually semi-rigid and/or partial strength and; (ii) the stiffness provided by the adjacent members (bending, axial or torsional stiffness).

Obtaining detailed experimental evidence of the behaviour of steel members subjected to realistic fire conditions is quite difficult and expensive. Natural fire tests, such as the Cardington tests [1] are of course ideal as they reproduce reality very closely but it is quite difficult to obtain detailed measurements of the mechanical response of individual members and to quantify the various parameters that control their behaviour. Available sub-frame tests are few and are usually unable to reproduce the transient temperature conditions that occur along the length of the members. It is therefore useful to develop numerical models to assess the behaviour of steel sub-frames subjected to fire.

Steel sub-frames were studied in Huang *et al* [2], Santiago *et al* [3], Hao *et al* [4]. The beam and columns are usually modelled by beam elements with the appropriate number of degrees of freedom, allowing in plane and out-of-plane bending and shear deformation, while the joint behaviour is simulated by an assumed moment-rotation relationship. Large displacements are also required to reproduce catenary action. However, under fire conditions, large variable axial forces due to the restraint to thermal expansion during the heating phase and to thermal contraction during the cooling phase can be observed. This axial force, in combination with bending moment and shear force in the connection area induces local buck-

ling and distortional buckling. Beam elements cannot realistically model local and distortional buckling; therefore, shell or solid elements should be used. Liu [5] and Lui and Davies [6] used a three-dimensional model created by isoparametric shell finite elements and beam-spring elements to model an internal bolted joint consisting of two identical cantilevers attached to a column. Comparisons against available tests results have shown good agreement. Yin and Wang [7] emphasized the effect of the axial and rotational restraints at the beam ends in the survival temperature in fire. They calibrated a numerical model against experimental results of fire tests on a restrained steel beam [6], [8] and carried out a parametric study on the parameters that affect the development of catenary action in a steel beam. Beam and end-plate were simulated by shell elements while the end restraints were modelled by elastic springs: axial restraint at the centroid of the beam and rotational restraints by two springs near the top and bottom of the beam. These studies were focused on the analysis of the influence of the joint and end restraints on the beam behaviour, specially force redistribution and displacements at high temperatures. Furthermore, with the exception of Santiago *et al* [3], all used a "nominal" fire loading, constantly increasing temperature (ISO curve), so that the effect of the cooling phase was not considered. However, during the cooling phase the plastically deformed beam contracts significantly and some connection components experience tensile forces [9].

Complementary to the experimental and numerical studies, some researchers try to simplify the problem by deriving prescribed equations to analyse restrained beams [10]. These equations are in line of the design procedures allowed by the Eurocode standards, but they need calibration against experimental or numerical results due to the simplifying assumptions: they work only in the elastic range and ignore the yielding and catenary effects that result at high temperatures.

The main objective of this paper is to propose a three-dimensional numerical model for a welded steel sub-frame using shell elements. The following phenomena are considered: the local failure modes; the influence of the heating and cooling phases and the response of the substructure; and the influence of several parameters relevant for the beam design. The main parameters are: temperature variation within the beam cross-section and along the beam, lateral torsional restraints on the top beam flange, beam span/depth ratio and mechanical load factor. The study cases are listed in Table 1. The temperature results measured in the 7th Cardington fire test, Wald *et al* [11], are considered.

Table 1: Overview of the parametric study.

Parameter	Study cases
Gradient temperature within the beam cross-section	i) Cardington beam temperature; ii) large temperature gradient within the cross-section; iii) uniform temperature within the cross-section
Gradient temperature along the beam span	i) Cardington beam temperature along the beam span; ii) lower temperature on 100mm from the joint.
Lateral-torsional restraint	i) top beam flange restrained; ii) beam unrestrained
Beam length	i) span/depth ratio = 19.3; ii) span/depth ratio = 9.7; iii) span/depth ratio = 14.5; iii) span/depth ratio = 29
Mechanical load factor	i) $P_{fi,d} = 20\% P_{Rd}$; ii) $P_{fi,d} = 12\% P_{Rd}$; iii) $P_{fi,d} = 40\% P_{Rd}$; iv) $P_{fi,d} = 60\% P_{Rd}$; v) $P_{fi,d} = 80\% P_{Rd}$. P_{Rd} is the uniform distributed loading corresponding to the design moment resistance of the simple supported beam at room temperature.

2   NUMERICAL MODEL

2.1   Introduction

In order to explore the behaviour of a sub-frame steel system under fire loading, the structure of Figure 1 was chosen. It consists of two HEA300 cross-section columns welded to an IPE300 cross-section beam with 5.7 *m* free span, supporting a 150 *mm* thick steel-concrete composite slab. The beam was assumed unprotected and the top flange unexposed to the fire load, while the column is thermally protected and unexposed to the fire load. This structural model corresponds to an experimental fire test programme carried out at the University of Coimbra in Portugal [12]. It also corresponds to a representative sub-structure of the 7th Cardington fire compartment test [11], [13]. The specification of the thermal loading (time-temperature-space variation) on the sub-structure was the measured transient temperatures.
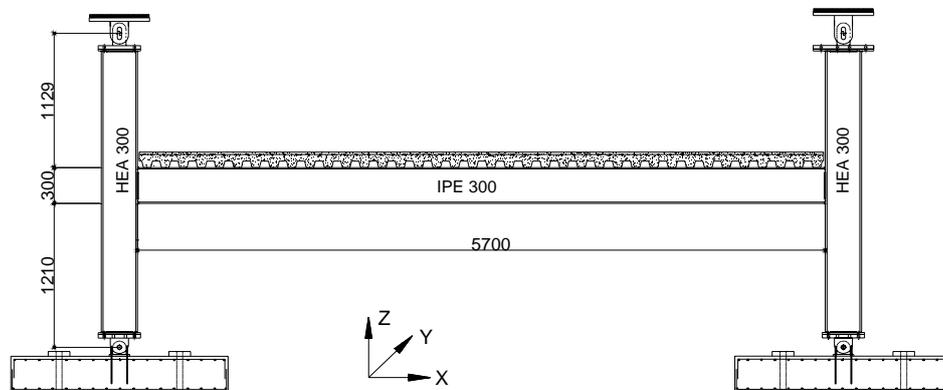

Figure 1: Sub-structure model (*mm*).

As stated in the introduction, the degree of restraint at the beam ends is crucial for the re-distribution of forces that takes place throughout the fire. It is thus useful to establish a non-dimensional measure of the restraint provided by the columns to the beam. The axial and rotational stiffnesses of the column at the beam level are given by:

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$$K_a = \frac{3E_cI_c}{L_{sup}^3} + \frac{3E_cI_c}{L_{inf}^3} = 100715.6 \; kN/m \qquad (1)$$

$$K_r = \frac{3E_cI_c}{L_{sup}} + \frac{3E_cI_c}{L_{inf}} = 174530.5 \; kNm \qquad (2)$$

where E_c is the Young modulus of the column, I_c the second moment of area of the column, L_{sup} the upper length of the column and L_{inf} the lower length of the column. The corresponding non-dimensional axial and rotational restraint ratios are given by:

$$\beta_a = \frac{K_a}{E_b \dfrac{A_b}{L_b}} = 0.508 \qquad (3)$$

$$\beta_r = \frac{K_r}{4E_b \dfrac{I_b}{L_b}} = 14.17 \qquad (4)$$

where E_b is the Young modulus of the beam, I_b the second moment of area of the beam, A_b the area of the beam and L_b the length of the beam.

In the following section, the implemented numerical model will be described in detail. The numerical model was modeled and calculated using the finite element code LUSAS [15].

2.2 Material properties

The assumed material of steel beam and columns at room temperature corresponds to the nominal law of S355. In order to perform a nonlinear geometrical analysis, this curve was modified to the true stress-logarithmic strain law as explained in Figure 2. The steel is nonlinearly temperature dependent and therefore material properties, as given in EN 1993-1-2 [14], were used in the FE model. The effect of creep on the deformation of steel has been considered indirectly through the use of the conventional stress-strain-temperature relationship suggested by EN 1993-1-2.
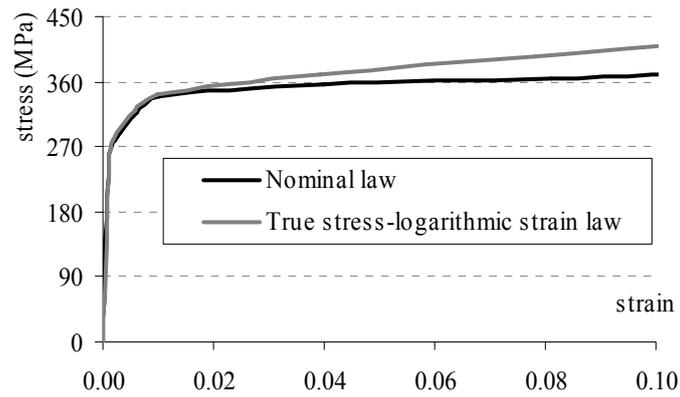
Figure 2: Stress-strain relationship of steel at room temperature.

2.3   Finite elements and mesh discretization

The numerical analysis was performed with the FE code LUSAS [15]. In order to reduce the model size and subsequent processing time, symmetry conditions were imposed at the beam mid-span. Three-dimensional eight-noded thick shell elements with five degrees of freedom per node (u, v, w, θ_α, θ_β) referred to the axes shown in Figure 3 were employed. Its formulation accounts for shear, bending and membrane internal forces. The FE mesh depicted in Figure 3 complies with the requirements for a reliable simulation and satisfies the mesh convergence study performed within the framework of this research work. This model has 2918 elements and 9068 nodes.
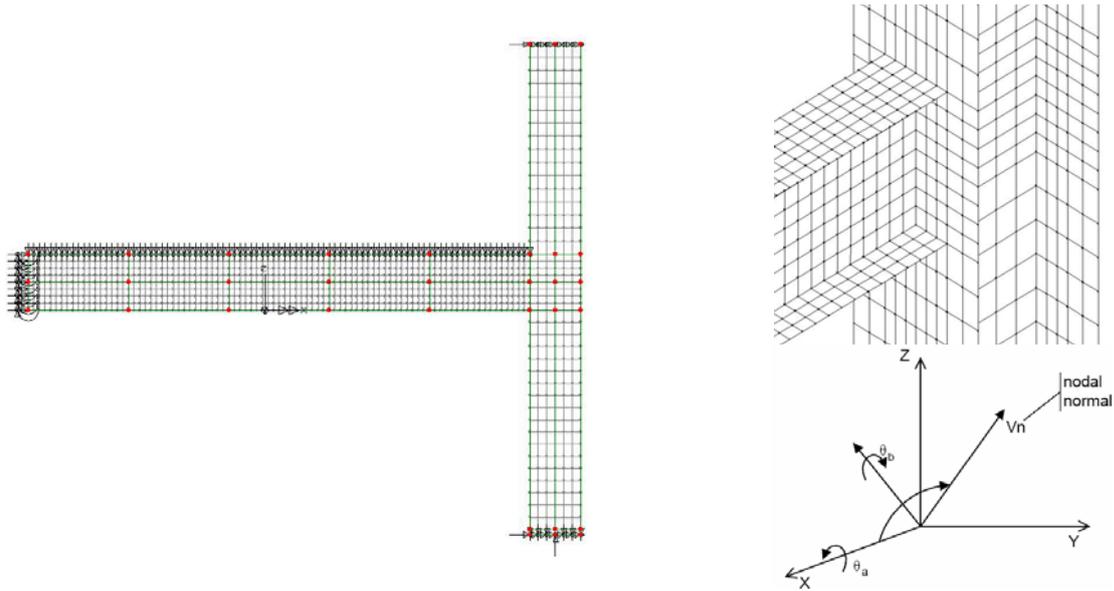
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Figure 3: Finite element model.

The concrete slab was not modeled as it only provided thermal boundary conditions for the temperature and lateral restraint to the beam top flange (non-composite behaviour).

2.4 Imperfections

In the beam, lateral geometrical imperfections were considered while the residual stresses were neglected. A lateral geometrical imperfection given by expression (5) was considered in accordance to prEN 1090-2:2007 [16] and Greiner [17]. An initial rotation around the x axis with a maximum value of $L/1000$ at mid-span and a curvature on the beam web with a maximum value of 4 *mm* at the mid-web were also introduced (Figure 4).

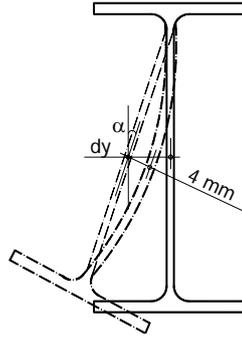$$y(x) = \frac{L}{1000} sin\left(\frac{\pi x}{L}\right) \tag{5}$$

Figure 4: Local geometric imperfection on the beam cross-section.

2.5   Loading and boundary conditions

Symmetry conditions were enforced at mid span of the beam, the axial displacement in the X direction was restrained as well as the rotations around the Y and Z directions. Displacements in the X, Y and Z directions were restrained at the bottom of the column, while the top of the columns was only restrained in the X and Y directions. In the reference case it was considered that the beam was restrained by a concrete slab: displacement in the Y direction was thus prevented at the top flange of the beam.

The mechanical loading applied at room temperature corresponds to the self-weight and a uniform loading of 10 *kN/m* distributed along the top flange of the beam, which corresponds to about 20% of the beam resistance at room temperature. This loading was applied at room temperature and remained constant throughout the analysis. The assumed thermal loading on the beam is shown in Figure 5, and corresponds to a fire curve with heating and cooling phases that reproduces the beam mid-span temperatures observed during the 7th Cardington fire test [11]. To avoid numerical convergence problems related to very low values of stiffness and yield stress of steel, slightly lower maximum temperatures than those observed experimentally were adopted (dotted line). Because the columns were fire protected they are assumed to remain at room temperature.
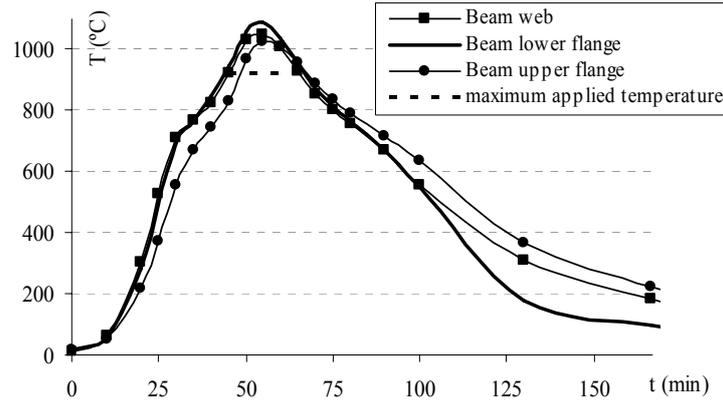
Figure 5: Thermal loading.

2.6 Nonlinear solution strategies

The integration algorithm is of implicit type (implicit backward Euler), which ensures a quadratic convergence to the iteration procedure associated with the Newton-Raphson method. The kinematic description of shell elements in a nonlinear geometrical analysis is based on the Total Lagrangian formulation, which accounts for large displacements and small strains; in this formulation stresses and strains are output in terms of the "second Piola-Kirchoff stresses" and "Green Lagrange strains" with reference to the undeformed configuration. This requires the use of a true stress-logarithmic strain measure $(\sigma_n - \varepsilon_n)$ for the definition of the uniaxial material response, instead of the classic engineering constitutive law $(\sigma - \varepsilon)$ (Figure 2). Both measures are related by the following relationship, Malvern [18]:

$$\sigma_n = \sigma(1 + \varepsilon) \text{ and } \varepsilon_n = \ln(1 + \varepsilon) \tag{6}$$

To account for the material nonlinearity, the von Mises yield criterion with nonlinear isotropic hardening was used. In the FE code LUSAS, the influence of the temperature on the elastoplastic response of the materials is represented in an approximate manner by calculating the elastic stresses using updated temperature dependent properties. The elastic predictor or trial stress σ at time $t + \Delta t$ is evaluated in the following way:

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a) Elastically unloading the structure at time t, using the material modulus interpolated at temperature θ, i.e.

$$\sigma^* = {}^{t}\sigma - {}^{t}D \cdot {}^{t}\varepsilon^{e} \quad \text{where} \quad {}^{t}\varepsilon^{e} = {}^{t}\varepsilon - {}^{t}\varepsilon^{p} \tag{7}$$

b) Elastically re-loading the structure at time $t + \Delta t$, using the material modulus interpolated at temperature $\theta^{t+\Delta t}$, i.e.

$$ {}^{t+\Delta t}\sigma = \sigma^* + {}^{t+\Delta t}D\left({}^{t}\varepsilon^{e} + \Delta\varepsilon\right) \quad \text{where} \quad \Delta\varepsilon = {}^{t+\Delta t}\varepsilon - {}^{t}\varepsilon \tag{8}$$

where ${}^{t}\sigma$ is the stress at time t, ${}^{t}D$ and ${}^{t+\Delta t}D$ are the stiffness matrices at time t and $t+\Delta t$, respectively, and ${}^{t}\varepsilon$ and ${}^{t+\Delta t}\varepsilon$ are the strains at time t and $t+\Delta t$, respectively.

2.7 Failure criteria

In order to assess the occurrence of failure throughout the fire event, a failure criteria is required. The failure conditions can be established by assuming that cracking occurs when the ultimate strain ε_{u} is attained. The failure should be assessed by comparing the maximum equivalent strain $\varepsilon_{E,max}$ with ε_{u}. Literature indicates that at high temperatures, the ultimate strain for high strength bolts is about 1-6%, Li *et al* [19], and for constructional steel, ultimate strains of 20% may be expected EN 1993-1-2[14].

3 REFERENCE CASE: BEHAVIOUR AND VALIDATION OF THE NUMERICAL MODEL

3.1 Introduction

To provide the basis for the various parametric studies, a reference case was established. It consists of the structural model of Figure 1. With respect to Table 1, it corresponds to:

i) gradient temperature within the cross-section that corresponds to the Cardington temperature at the beam mid-span. Gradient temperature along the beam span was not considered;

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ii) top flange of the beam continuously restrained;

iii) a span/depth ratio of 19.3, corresponding to a free span of $L_0 = 5700$ *mm*;

iv) a mechanical load factor $P_{fi,d} = 20\% \, P_{Rd}$.

Because of the complexity of performing a transient temperature nonlinear numerical analysis of a steel structure with temperature varying material properties, this reference case was analyzed using two different FE programs. LUSAS [15], a general purpose commercial non-linear finite element code was used throughout this study, while SAFIR [20], a special-ized finite element code specifically developed for the analysis of structures subjected to fire was only used for the reference case, to provide additional validation of the numerical results.

In the case of LUSAS, all calculations were carried out using shell elements, as it was al-ready described in item 2.3, while for SAFIR two alternative analyses were performed using beam and shell elements.

3.2   Global behaviour

Figure 6 illustrates the variation of the mid-span deflections of the beam throughout the fire, for the 3 FE models. For all cases, this variation is markedly different during the analysis. It starts gradually but, as the lower beam flange temperature rises above 550 *ºC* ($t = 25$ *min*), the rate of deformation increases significantly. At the maximum temperature, the mid-span deflection was about 0.34 *m*, corresponding to $L/8$, $L/20$ being the usual maximum deflection at the fire limit state, BS 476 [21]. During the cooling phase, since the material has been stressed beyond the elastic limit, the corresponding strain does not follow the same stress-strain path as during the heating phase and a plastic deflection is observed: 0.27 *m*.
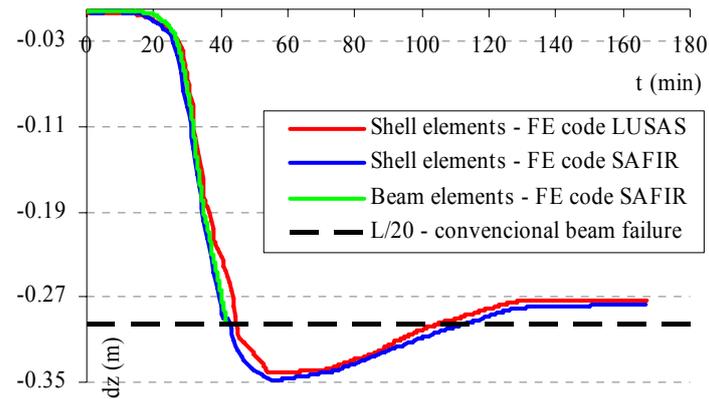
Figure 6: Development of the mid-span deflection during the fire.

It is noted that the analysis using beam elements is unable to follow the cooling phase, the model becoming numerically unstable before reaching the maximum temperature. Both analyses using shell elements show good agreement.

Figure 7 illustrates the development of the axial force and bending moment at mid-span of the beam (cross section A) and at a cross-section 0.03 *m* away from the column flange– cross section B). For the shell models, the axial force was calculated by equilibrium and by the integration of the normal stresses at the cross-section B while the bending moment is always calculated by taking moments with respect to the beam bottom flange axis.
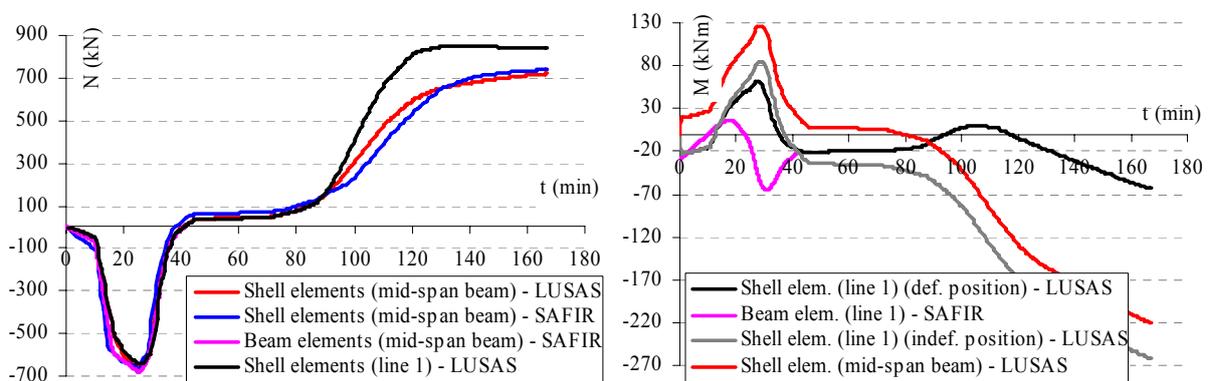

Figure 7: Development of the beam axial force and bending moment during the fire.

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The analysis of the development of the internal forces should be divided into different stages. In Phase *1* (*t* < 9 *min*) the thermal expansion was converted into thermal stresses that increased the level of axial compression and sagging moment without large displacements (Figure 6). Phase *2*, that starts approximately after 9 *min* of the fire exposure, corresponds to the increase of the internal forces. In Phase *3* (26 *min* < *t* < 45 *min*) a decrease of the internal forces is noted because of the material strength degradation and large deflections. In Phase *4* (45 *min* < *t* < 55 *min*), the beam behaviour changes from bending to catenary action and tensile forces are developed. Bending moments reduce and become similar to those observed at room temperature. Phase *5* (*t* < 55 *min*) corresponds to the cooling phase – increasing of the tensile forces and hogging moment because of the recovering of strength and stiffness. At about *t* = 125 *min*, because the cooling rate reduces and the beam reaches temperatures lower than 400 *ºC*, and the bottom flange temperature is lower than 200 *ºC*, the rate of development of the mid-span deflection and internal forces also decrease. It is finally noted that during cooling the axial force is not constant along the beam.

3.3 Local behaviour at the joints

Figure 8 shows the evolution of deformation with time around the joint area. Local buckling of the beam bottom flange and shear buckling at the web in the vicinity of the joint were the main failure mechanisms. This local buckling occurs during the heating phase after about 30 *min* of fire, due to the restraint to thermal elongation provided by the adjacent cooler column. The heated bottom flange of the beam is insufficient to transmit to the column the high normal forces generated by the thermal stresses; subsequently, these forces are partially transferred to the heated web, that is also unable to transfer them to the column and buckling is developed. The beam could be assumed to behave as 'simply supported', allowing larger mid-span deflections to develop (Figure 6).
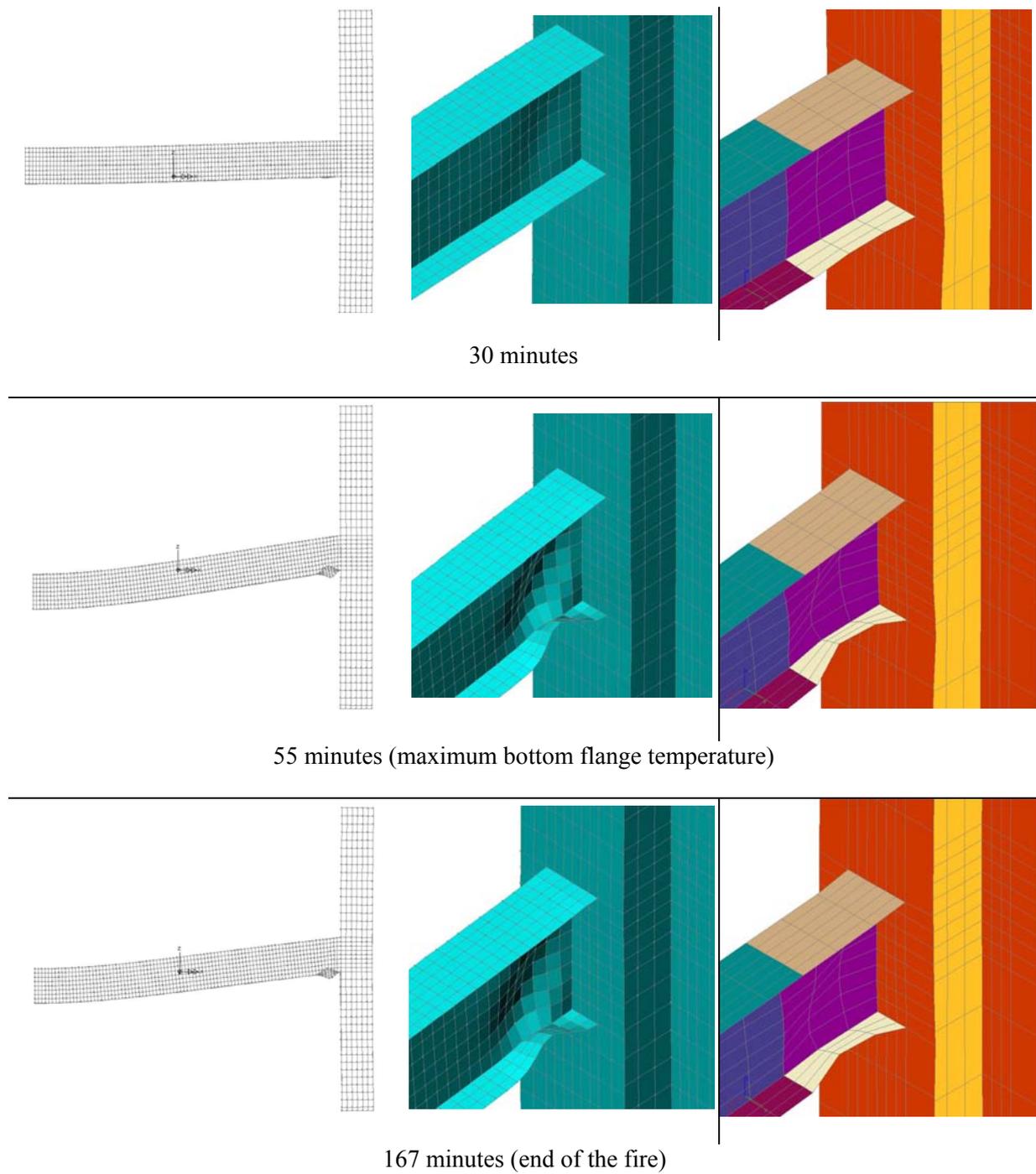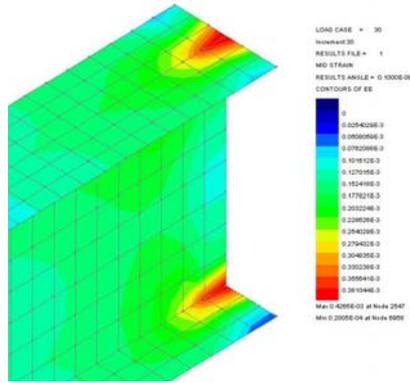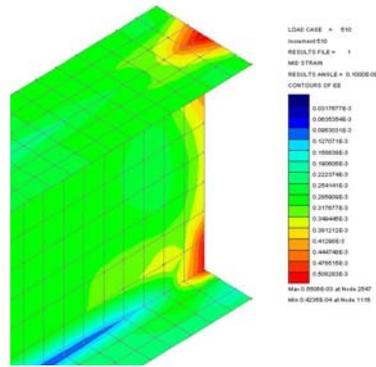
30 minutes

55 minutes (maximum bottom flange temperature)

167 minutes (end of the fire)

Figure 8: Deformed mesh (LUSAS – left side; SAFIR – right side). Scale factor is 1.0.

Figure 9 shows the development of the equivalent strains, ε_E [22] in the vicinity of the joint. Figure 10 depicts the corresponding axial forces, as well as the beginning of the yield-
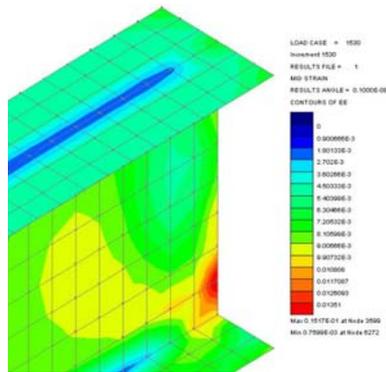
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ing at each beam zone ($^{t}\sigma_{E} \geq {}^{t}f_{y}$; where $^{t}\sigma_{E}$ and $^{t}f_{y}$ are the equivalent stress and the yield stress at time t. Also for the joint behaviour distinct phases during the fire can be identified: before the start of the fire, uniform tensile and compressive bands along the alignment of the top and bottom flanges of the beam are present, due to the mechanical loading. On the web panel a state of almost pure shear is observed. These stresses and strains on the top and bottom flanges of the beam are *mechanical strains*. As the temperature starts to increase (phase *1*), *thermal strains* are also introduced (positive strains) that increase the total strain in the top flange and decrease it in the bottom flange ($t = 9$ *min.*). Some of these *thermal strains* are converted into stresses which increase the axial compressive force. Beyond a temperature of 100 *°C* (phase *2*), the elastic modulus reduces with temperature and the *mechanical strains* also increase. Beyond 400 *°C* (phases *3 and 4*), *total strains* continue to increase. In the joint these strains are converted in stresses; however, due to the reduction of the yield stress with temperature, stresses on the beam decrease. Due to the high stiffness of the column, that remains at room temperature, and the local massivity of the joint compared with the beam, the high strains observed on the beam bottom flange move way from the joint - 100-110 *mm* (26 *min*). The maximum value of the equivalent strain is $\varepsilon_{E} = 27$ % and it is observed in the interface bottom flange - web at $t = 50$ *min* ($\theta_{\text{bottom flange}} = 890$ *°C*). Theses high strains induce the local buckling observed in Figure 8. At these high temperatures, the bottom flange has low compressive strength, the band of stresses and strains spreads up to the web and shear buckling in the web is also observed. Once the cooling phase starts (phase *5*) the thermal strains begin to reduce. This induces a reversal of the deflection (Figure 6) generating tensile axial forces in the web and bottom flange and compressive axial forces in the top flange (166 *min*).
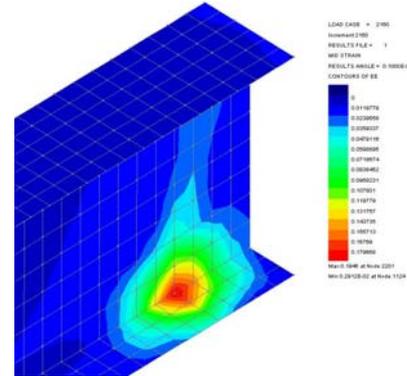
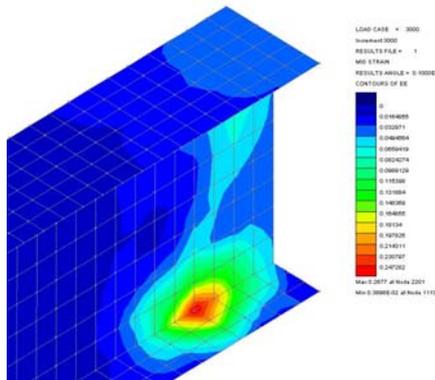$t = 0.5\ min.\ (\varepsilon_{Emax} = 0.39\text{E-}3)$ $t = 8.5\ min.\ (\varepsilon_{Emax} = 0.47\text{E-}3)$
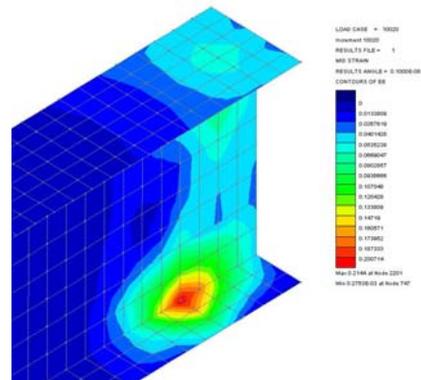
$t = 26\ min.\ (\varepsilon_{Emax} = 0.015)$ $t = 36\ min.\ (\varepsilon_{Emax} = 0.19)$

$t = 50\ min.\ (\varepsilon_{Emax} = 0.27)$ $t = 166\ min.\ (\varepsilon_{Emax} = 0.21)$

Figure 9: Development of the maximum equivalent strains in the beam near the connection.
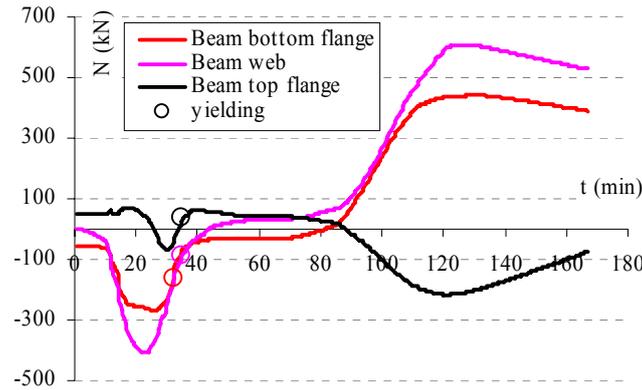
Figure 10: Axial forces developed in the beam at 0.03 *m* from the column flange (cross section B).

4 INFLUENCE OF THE BEAM SPAN-TO-DEPTH RATIO

In order to assess the influence of the beam span-to-depth ratio, four different spans were considered for the sub-structure model of Figure 1: 2850 *mm*, 4275 *mm*, 5700 *mm* and 8550 *mm*, corresponding to 50%, 75%, 100% and 150% of the span of the reference case (L_0). Given that the cross-section of the beam is kept constant (IPE300), the corresponding span-to-depth ratios vary between 9.7 and 29, representing a range that is fairly typical of practical designs. For consistency, the mechanical load level on the beams was adjusted to give a constant load ratio of $P_{\text{fi,d}}$ = 20% P_{Rd}. Table 2 lists the resulting uniformly distributed loads, together with the corresponding axial and rotational restraint ratios.

Table 2: Beam span-to-depth ration: study cases.

L/L_0	L	Span/depth	$P_{\text{fi,d}}$	P (kN/m)	βa	βr
0.5	2850	9.7	20%	40.0	0.25	7.09
0.75	4000	14.5	20%	17.8	0.36	9.95
1.0	5700	19.3	20%	10.0	0. 51	14.17
1.5	8550	29	20%	4.44	0.76	21.26

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For the longer beam spans, the failure mode is similar to the observed for the reference case. For the short beam spans, low bending and axial deformations are observed and large compressive deformations in the web and bottom flange are developed.

Figure 11 shows that when the beam behaviour is controlled by bending at low temperatures, a longer beam span gives larger beam deflections. At high temperatures, when the beam behaviour is controlled by catenary action, all beam deflections converge (45 *min*), except for $L = 1.5 \, L_0$, due to the previous large deflections that already occurred at low temperatures. During the cooling phase, the rate of recovery is dependent on the beam span. Long beam spans show the highest rate of deflection reduction.
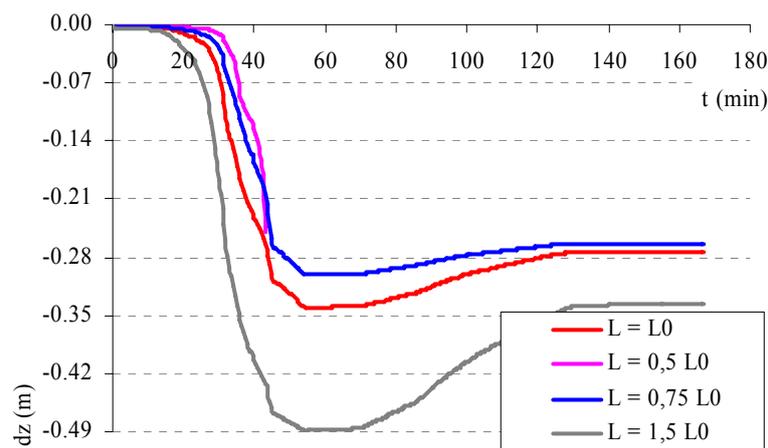

Figure 11: Development of the mid-span deflection during the fire.

At low temperatures, the compression force varies with the beam span, due to different rate of thermal expansion (Figure 12). As the temperature increases and the axial stiffness decreases, this different rate is more noticeable. Long beams have higher compression forces. The compression force starts to drop at a slightly lower temperature for the longer beam spans, but the start of the decrease of compression displacement is independent of the beam span. At high temperatures, because the beams have the same cross-sectional area, they behave simi-

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larly and have almost the same catenary force, indicating a minor influence of the beam bending resistance. The tensile axial force is independent of the beam span during the cooling phase. In all cases, the axial forces are within the bounds corresponding to the tensile capacity [14], but in the case $L = 0.5\ L_0$, the beam fails when the maximum catenary force reaches the tensile capacity.
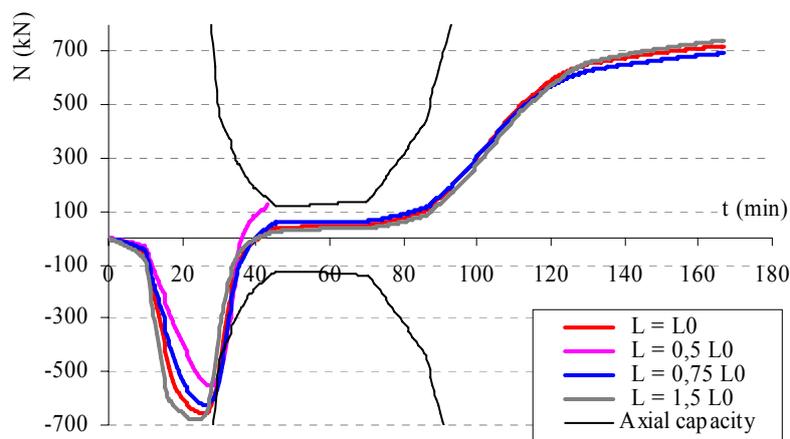
Figure 12: Development of the beam axial force during the fire.

Figure 13 shows that for the short beams, the maximum equivalent strains near the joint are located at the top of the cross-section. However, as the beam span increases, the maximum equivalent strains decrease and shifts towards the bottom beam flange.
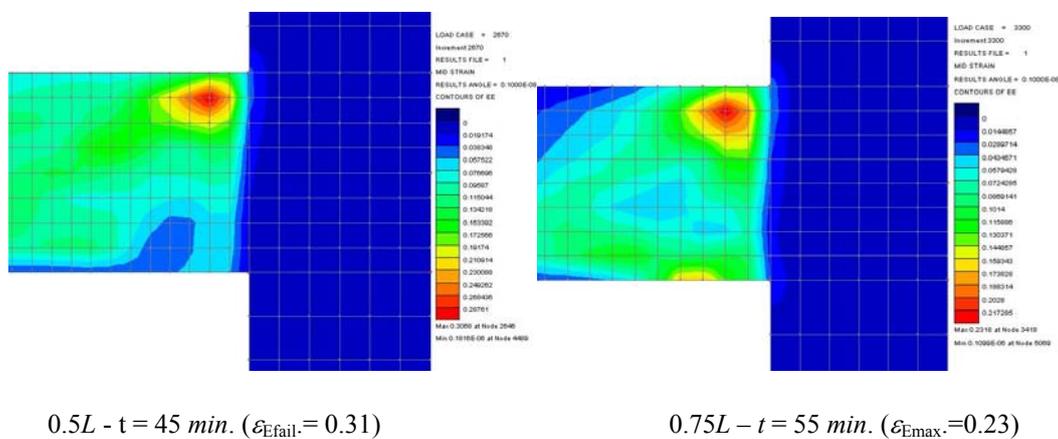
$0.5L$ - t = 45 min. ($\varepsilon_{Efail.}$= 0.31) $0.75L - t = 55\ min$. ($\varepsilon_{Emax.}$=0.23)

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<div align="center">1.0<i>L</i> - <i>t</i> = 50 <i>min</i>. ($\varepsilon_{Emax.}$= 0.27)   1.5<i>L</i> - <i>t</i> = 50 <i>min</i>. ($\varepsilon_{Emax.}$= 0.23)</div>

<div align="center">Figure 13: Development of the maximum equivalent strains in the joint.</div>

5   INFLUENCE OF TEMPERATURE GRADIENT WITHIN THE BEAM CROSS SECTION

Gradient temperature within the beam cross-section is usually the result of the heat sink effect of the concrete slab on the top flange. Special reference on the study of the temperature gradient effect within the beam cross section on the structural behaviour is made to Yin and Wang [7] that demonstrate that the temperature gradient has a small influence on the development of the catenary action at high temperatures. In the following, the temperature gradient effect on the local joint behaviour is discussed. The results for the reference case (case a) are compared with two other different cases (Figure 14):

i) Case b: uniform temperature within the beam cross-section that corresponds to the bottom beam flange temperature of the reference case; and

ii) Case c: large gradient temperature, the bottom flange and web having the same temperature as the reference case but the top flange temperature is reduced.
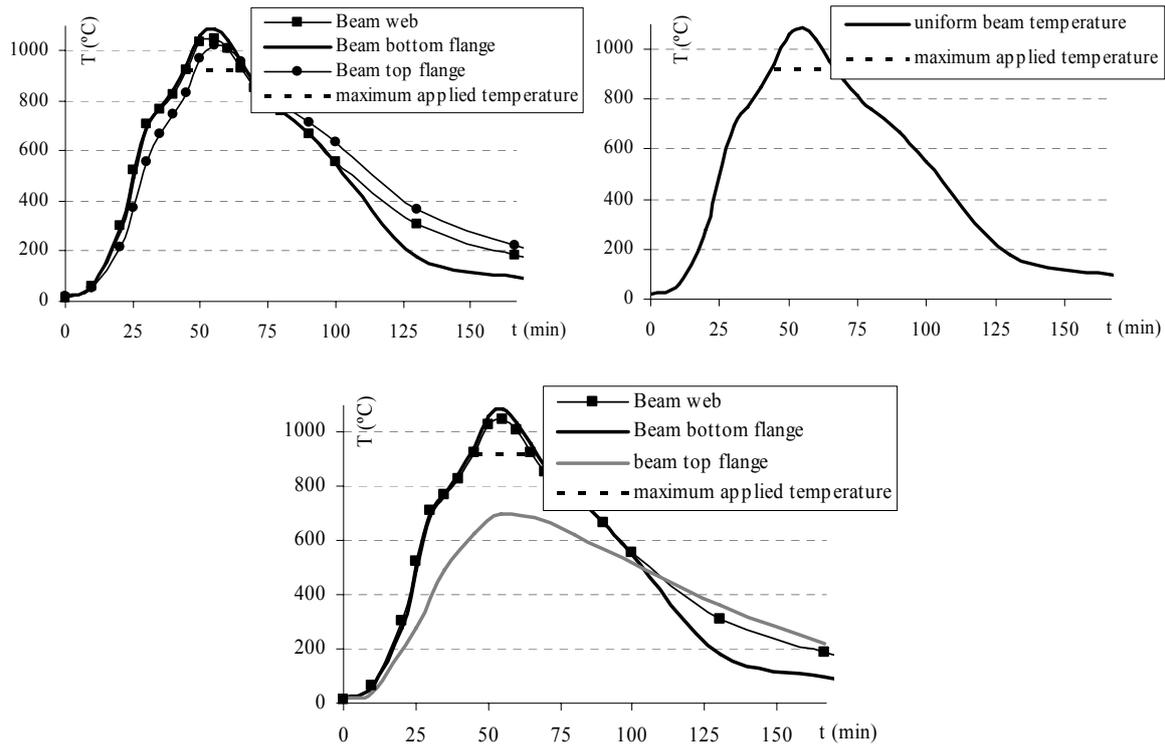
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Figure 14: Thermal loading: a) reference case; b) uniform temperature and c) large gradient temperature .

When the cross-section is subjected to a non-uniform temperature profile, differential expansion occurs in each fibre and curvature is observed. Figure 15 compares the beam midspan deflection for the three cases. All curves have a similar pattern, but some points are noticeably different: at high temperatures, case c shows the lowest maximum deflection because the lower temperature in the top flange. Case b deflected faster, reaching the maximum deflection at $t = 45$ *min* that corresponds to the maximum temperature in whole cross-section; for case c, the bottom flange and the web reached the maximum temperature at $t = 45$ *min*, but the maximum top flange temperature is only reached at $t = 54$ *min*. During the cooling phase, for case c the bottom flange temperature decreased faster than the web and the top flange, leading to a faster reduction of deflection.

Although case b showed the highest internal forces in the beam and is considered the critical thermal load for the design of steel members, the equivalent strain contours were sof-

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tened around the joint area, while in the non-uniform temperature cases, large equivalent strains are concentrated in the lower zone of the beam, where the maximum temperatures are introduced.
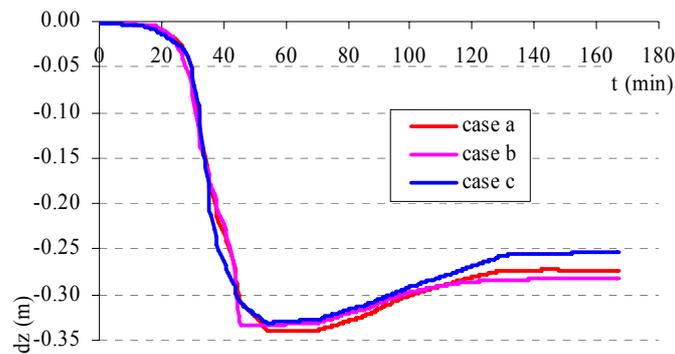

Figure 15: Development of the mid-span deflection during the fire.

6   INFLUENCE OF TEMPERATURE GRADIENT ALONG THE BEAM SPAN

Variations of temperature are usually only studied across the cross-section and it is assumed that the gradient temperature along the beam span is constant, EN 1993-1-2 [14]. Experimental observations show that due to the concentration of mass near the joints they exhibit different temperatures throughout the fire, Wald *et al*. [13]. In this study, the reference temperature (case a) was compared to a temperature gradient along the beam span that reproduces the measured joint temperatures (case b), as shown in Figure 16.
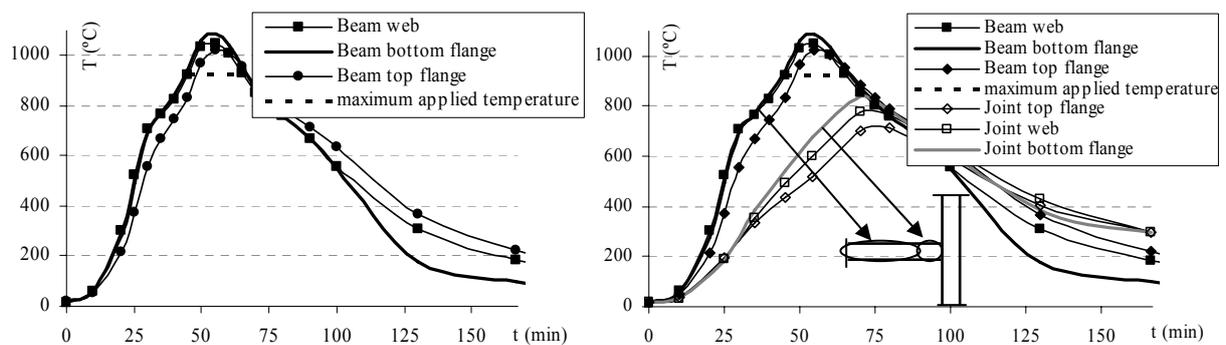
Figure 16: Thermal loading: a) reference case; b) temperature gradient along the beam span.

Figure 17 compares the mid-span deflection for both cases. A lowest maximum tempera-
ture (10 to 15%) near the joint leads to a maximum displacement 15% lower than the refer-
ence case. During cooling, the recovery rate of deflection does not depend on the temperature
gradient along the beam span. In contrast to what is observed for the mid-span deflection, the
influence of the gradient temperature along the beam is irrelevant on the internal forces along
the beam. Small differences are observed during the cooling phase, because the temperature
at the bottom flange of the joint decreased slower than the beam bottom flange, leading to a
small increase of the sagging moment due to thermal bowing; although, the maximum strains
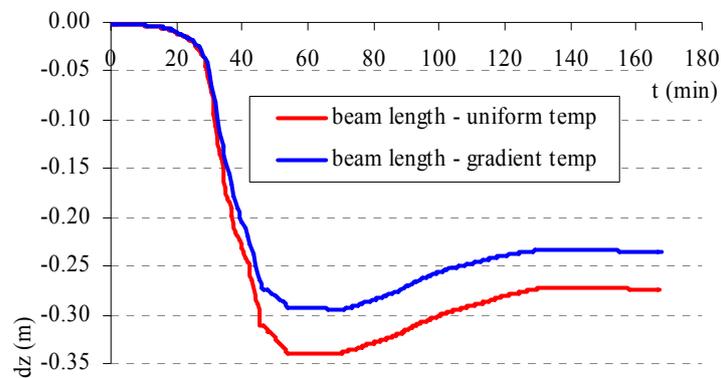are moved away from the joint.

Figure 17: Development of the mid-span deflection during the fire.

7 EFFECT OF LATERAL RESTRAINTS ON THE BEAM TOP FLANGE

Lateral torsional buckling is a relevant mode of failure for a steel beam at ambient and
elevated temperatures. Under fire conditions a number of relevant research studies on the lat-
eral torsional buckling of steel beams have been carried out. Bailey performed a numerical
analysis for beams under a uniform temperature distribution [23]. Vila Real and Piloto con-
ducted a few experiments of slender beams at uniform elevated temperatures [24] and Vila

Real and Franssen [25] carried out a numerical study and proposed a design method for lateral torsional buckling of steel beam under uniform temperature, which has been adopted in the current version of EN 1993-1-2. This design method was improved by Vila Real et *al*. [26]. Recently, Yin and Wang presented a numerical study for beam laterally unrestrained with uniform and non-uniform temperature and different axial end restraints [7], in which some considerations about the axial reactions and mid-span deflection are also made.

In the following, lateral torsional buckling is discussed. Initial imperfections were the same for restrained and unrestrained beam (see §2.4). Figure 18 compares the deformed mesh of the sub-structure restrained at the top flange with the evolution of the deformed mesh of the same model without lateral restraint.
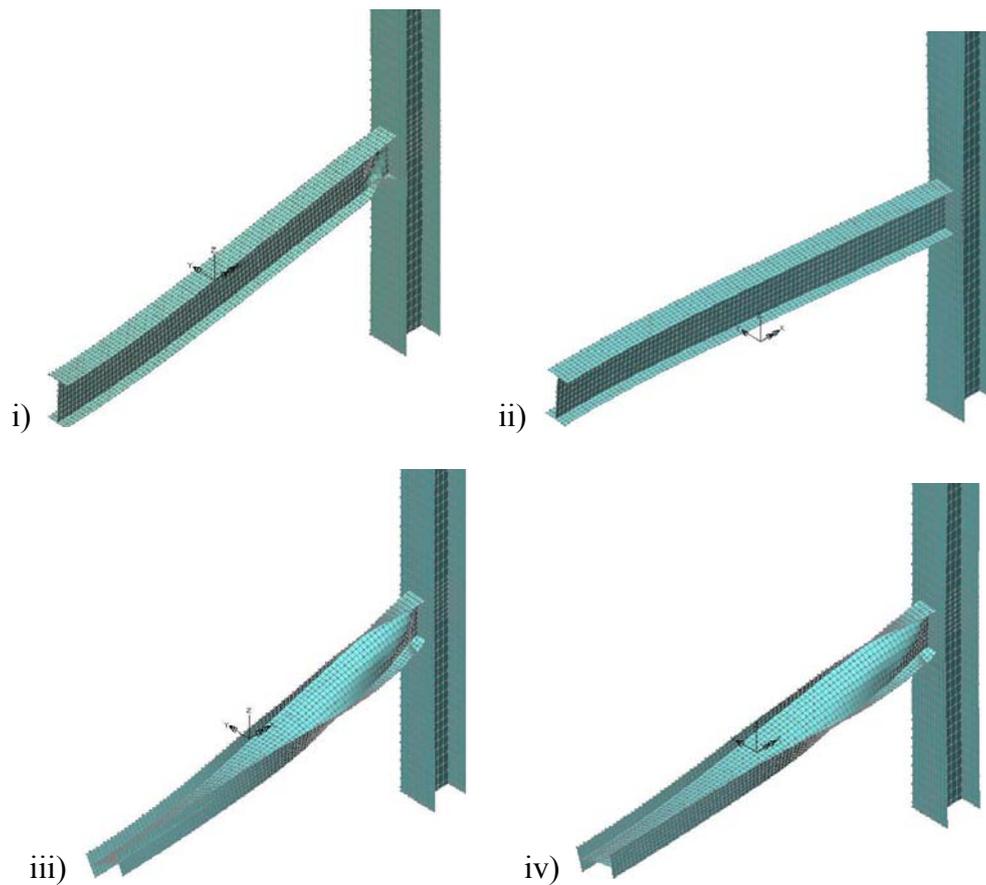
i)

ii)

iii)

iv)

Figure 18: Failure modes: i) restrained beam; ii) unrestrained beam (29 min.); iii) unrestrained beam (36 min.); iv) unrestrained beam (end of the fire – 166 *min*). Scale factor 1.0.

At low temperatures, the beam behaviour is governed by thermal expansion only, and low vertical and lateral displacements are observed (Figure 19). Approximately after 15 *min* the beam stiffness starts to decrease and an increase of lateral displacement without vertical displacements is observed. The axial force reduces (Figure 20) as the beam deflects laterally and no local buckling near the joint is observed (Figure 18). Due to the lateral movement of the unrestrained beam, the bending moment resistance is lower than for a beam with lateral restraints. Therefore, catenary action contributes more to the laterally unrestrained beam resistance. As the temperature increases, to the influence of catenary action is bigger than the bending and the lateral displacement of beam reduces so that the beam takes the original position while the large mid-span deflection is observed. Beyond this point, mid-span deflection is larger than the unrestrained beam (Figure 19). The presence of lateral restraints delays the temperature at which the catenary action is achieved. At elevated temperatures, the lateral displacement is negligible, and a torsional failure mode is evidenced until the end of the fire (Figure 18). The vertical deflection of both models converges during the cooling phase, reaching the same value at the end of the fire.
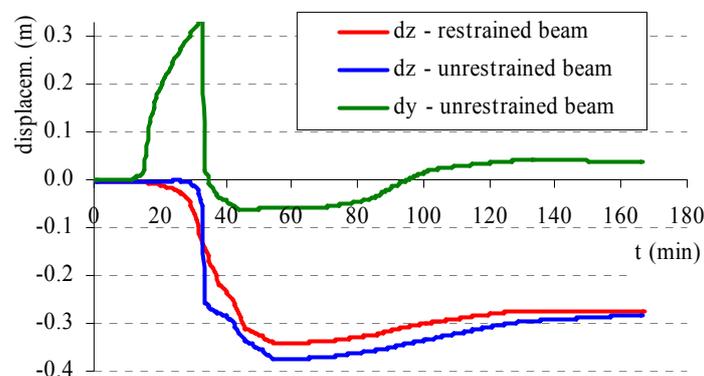
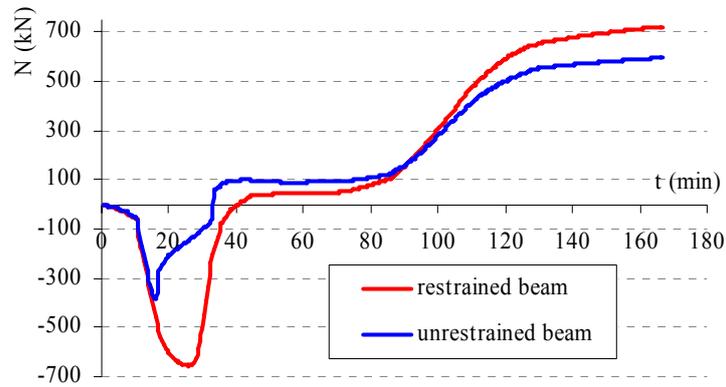Figure 19: Development of the mid-span deflection during the fire.

Figure 20: Development of the beam axial force during the fire.

Figure 21 compares the growth of bending moment against the fire evolution in the beam. At low temperatures, the bending moment development is similar in both cases. Bending moment starts to reduce as the beam starts to deflect laterally. Simultaneously, the lateral bending moment and the lateral rotation increase and reach maximum values at the instant corresponding to the maximum sagging moment of the restrained beam. The unrestrained beam reaches similar maximum lateral bending moment and maximum sagging bending moment. At elevated temperatures, the lateral bending moment reduces to negligible values and the hogging moment gets close to values similar to those observed on unrestrained beam. During the cooling phase, the lateral bending moment increases again
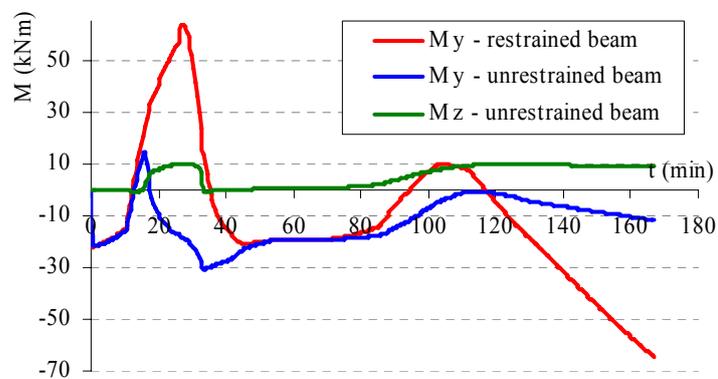

Figure 21: Development of the joint bending moment during the fire.

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8   EFFECT OF MECHANICAL LOAD FACTOR

In order to examine the effect of catenary action on the critical temperature of the beam, numerical simulations of restrained beams at different mechanical load levels were conducted by Liu [6] and Yin and Wang [7]. The results were compared to those obtained from experimental tests showing good agreement.

In this study, the reference case ($P_{\text{fi,d}}$ = 20% P_{rd}) was compared to four other cases: $P_{\text{fi,d}}$ = (12%; 40%; 60%; 80%) P_{rd}.

Due to the large torsional deformations at high load levels, a nominal deformation failure criteria was accepted. The numerical failure is assumed when the cross-section rotation is larger than 90º. This failure condition was observed in the case of a mechanical load higher than 60% P_{rd} and occurred during the heating phase. As for the other cases, the failure modes are similar to those observed for the reference case.

The deflection curves for the five levels of loading are shown in Figure 22. At low temperatures, beam deflection is dependent on the mechanical loading. A further rise in temperature leads to a progressive run-away of beam deflection as the loss of stiffness and strength accelerates; however, in the cases with low loading levels, the rate of run-way is reduced where the axial force is changing from compression to tension – catenary action (Figure 23). In the cases with high loading levels, excessive deflection accompanied by torsional deformation is observed and the beam fails. As for the other cases, whenever the cooling phase is reached, the heated beam begins to recover strength and stiffness, together with a reduction of thermal strains which induces a reversal of the deflection. The rate of deflection reduction is not dependent on the mechanical load level.
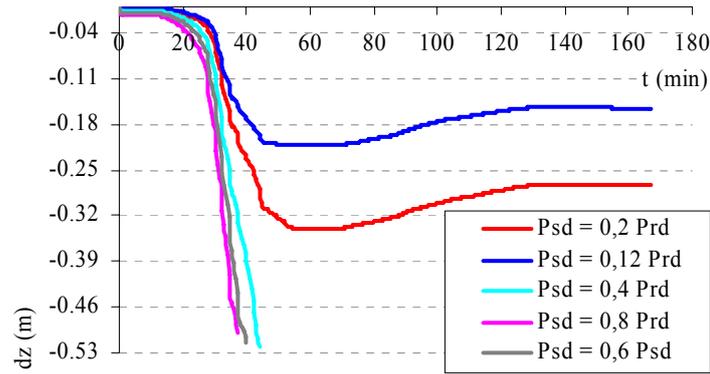
Figure 22: Development of the mid-span deflection during the fire.

Figure 23 plots the growth of the axial force and bending moment against time for the five loading levels. Axial force curves have similar gradients up to a fairly similar maximum of compressive force, confirming that they have similar rates of thermal expansion irrespective of the applied load level. When the stiffness starts to decrease, lower compression forces at higher loading levels are observed. The compression force starts to decrease at a slightly lower temperature in cases with higher loading level. This is followed by the onset of the vertical deflection run-away. At high loading levels, the compressive force quickly changes to a tensile force and failure is attained due to excessive mid-span deflection. At lower loading levels, the beam is supported by the catenary action which takes place earlier for beams with lower applied loading and a more obvious change of deflection gradient can be seen (Figure 22). A higher tensile force at higher loading levels is reached. During the cooling phase, the heated beam recovers strength and stiffness and lower tensile forces at higher loading level are observed.
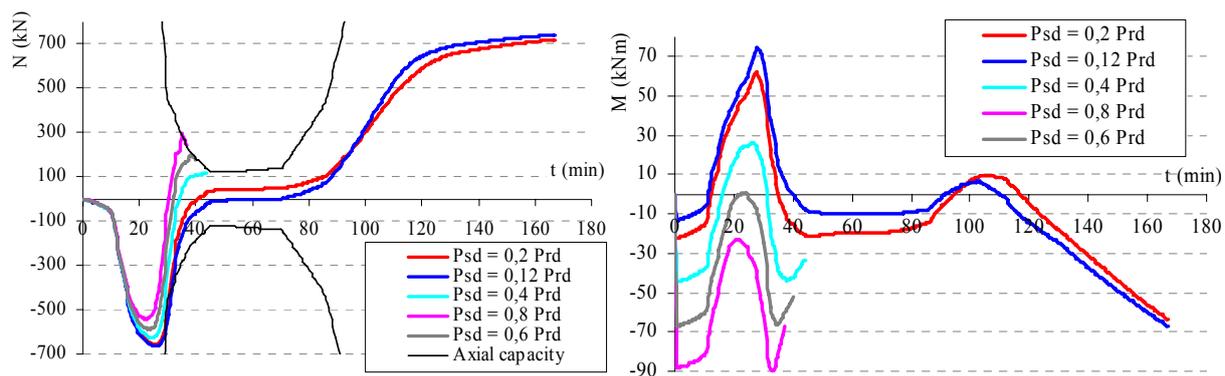
Figure 23: Development of the beam axial force and joint bending moment during the fire.

As the temperature increases, the bending moment also increases and the maximum bending moment is reached when the beam resistance started to decrease after 25 *min* at temperature of 400 *ºC*. The beams with high mechanical loading do not reach a sagging moment. Beyond that, the temperature continues to increase but the bending moment decreases until the room bending moment. In the cases where the beam failure is not observed before cooling, the bending moment and the rotation remain constant at high temperatures. The discontinuity of the bending moment curve due to the reversal thermal bowing during cooling is more noticeable in the high mechanical load cases. As the temperature continues to decrease to values below 500 *ºC* the hogging moments have reversed. Residual effects are clearly very important in these cases.

The effect of the mechanical loading on the distribution of strains is similar to the effect of the beam span: maximum strains spread up in the cross-section as the mechanical loading increase. However, the high equivalent strains observed on the upper zone of the cross-section of short beams occurred because of the shear buckling of the beam web due to high compression in the beam, while the high values on the higher load factor cases result from the high tensile forces due to the large bending deformations. As the mechanical loading increases, the critical component moves from the bottom flange in compression to the top flange in tension.

9 CONCLUDING REMARKS

This paper presented the results of a numerical study using LUSAS, FE software package, to analyse the behaviour of a beam-to column steel system under fire. In order to provide credibility to the FE modelling results obtained by LUSAS they were compared to a fire dedicated program – SAFIR. A numerical parametric study was conducted to investigate possible behaviour of the sub-frame. In this way, insight into the behaviour of the steel girder, which is the most usual structural element of a floor in multi-storey buildings, exposed to natural fire is gained. The main characteristics of every particular failure modes that correspond to certain geometry of the girder are discussed in the text. The constant shape of the initial imperfections, consisting of the local and global imperfections, was used independently of the geometry of the girder. This approach is consistent with proposed implementation of initial imperfections according to EN 1993-1-5. In some cases, when clear discrepancy between the realistically assumed imperfections and the final failure mode exists, one should repeat the computation assuming the initial imperfection in a shape of the failure mode obtained in order to obtain the lower boundary of the fire resistance. However, in the cases considered in this paper, no reasons were found eligible to perform the additional analysis. There were no doubts about the finding that no fire protection is necessary for the composite girders exposed to the natural fire scenario, as measured in 7th Cardington test. The parametric study also highlighted the influence of the end-restraints of the beam, thus indicating that behaviour is very much dependent of the joint characteristics and the degree of force redistribution that takes place as the fire progresses.

ACKNOWLEDGMENTS

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FIGURES CAPTIONS

Figure 1: Sub-structure model (mm).

Figure 2: Stress-strain relationship of steel at room temperature.

Figure 3: Finite element model.

Figure 4: Local geometric imperfection on the beam cross-section.

Figure 5: Thermal loading.

Figure 6: Development of the mid-span deflection during the fire.

Figure 7: Development of the beam axial force and bending moment during the fire.

Figure 8: deformed mesh (LUSAS – left side; SAFIR – right side). Factor scale: x1.

Figure 9: Development of the maximum equivalent strains in the joint.

Figure 10: Axial forces developed in the beam in the vicinity of the joint (line1).

Figure 11: Failure modes: i) $L = 0.5 L_0$ (43 min); ii) $L = 0.75 L_0$ (166 min.); iii) $L = L_0$ (166 min.); iv) $L = 1.5 L_0$ (166 min.). Factor scale: x1.

Figure 12: Development of the mid-span deflection during the fire.

Figure 13: Development of the beam axial force during the fire.

Figure 14: Development of the joint bending moment during the fire.

Figure 15: Development of the maximum equivalent strains in the joint.

Figure 16: Thermal loading: a) reference case; b) uniform temperature case and c) large gradient temperature case.

Figure 17: Development of the mid-span deflection during the fire.

Figure 18: Development of the beam axial force and joint bending moment during the fire.

Figure 19: Development of the maximum equivalent strains in the joint.

Figure 20: Axial forces developed at the beam element in the vicinity of the joint (line1).

Figure 21: Thermal loading: a) reference case; b) temperature gradient along the beam span.

Figure 22: Development of the mid-span deflection during the fire.

Figure 23: Development of the beam axial force and joint bending moment during the fire.

Figure 24: Development of the maximum equivalent strains in the joint.

Figure 25: Failure modes: i) restrained beam; ii) unrestrained beam (29 min.); iii) unrestrained beam (36 min.); iv) unrestrained beam (end of the fire). Factor scale: x1.

Figure 26: Development of the mid-span deflection during the fire.

Figure 27: Development of the beam axial force during the fire.

Figure 29: Development of the joint bending moment during the fire.

Figure 29: Development of the maximum equivalent strains in the joint.

Figure 30: Failure modes: i) p = 20% Prd; ii) p = 40% Prd (44 min.); iii) p = 60% Prd (38 min.); iv) p = 80% (35 min.). Factor scale: x1.

Figure 31: Development of the mid-span deflection during the fire.

Figure 32: Development of the beam axial force and joint bending moment during the fire.

Figure 33: Development of the maximum equivalent strains in the joint.

Figure 34: Axial stresses in the joint: $p_{fi,d} = 0.8\ p_{rd}$. t = 39 min. (failure).

TABLES

Table 1: Study cases.

Parameter	Study cases
Gradient temperature within the beam cross-section	i) Cardington beam temperature; ii) large temperature gradient within the cross-section; iii) uniform temperature within the cross-section
Gradient temperature along the beam span	i) Cardington beam temperature along the beam span; ii) lower temperature on 100mm from the joint.
Lateral-torsional restraint	i) top beam flange restrained; ii) beam unrestrained
Beam length	i) span/depth ratio = 19.3; ii) span/depth ratio = 9.7; iii) span/depth ratio = 14.5; iii) span/depth ratio = 29
Mechanical load factor	i) $p_{fi,d}$ = 20% p_{Rd}; ii) $p_{fi,d}$ = 12% p_{Rd}; iii) $p_{fi,d}$ = 40% p_{Rd}; iv) $p_{fi,d}$ = 40% p_{Rd}; v) $p_{fi,d}$ = 60% p_{Rd}; vi) $p_{fi,d}$ = 80% p_{Rd}. p_{Rd} is the uniform distributed loading corresponding to the design moment resistance of the simple supported beam at room temperature.

Table 2: Beam span-to-depth ration: study cases.

L/L0	L	Span/depth	Pfi,d	p	βa	βr
0.5	2850	9.7	0.2	40.0	0.25	7.09
0.75	4000	14.5	0.2	17.8	0.36	9.95
1.0	5700	19.3	0.2	10.0	0. 51	14.17
1.5	8550	29	0.2	4.44	0.76	21.26